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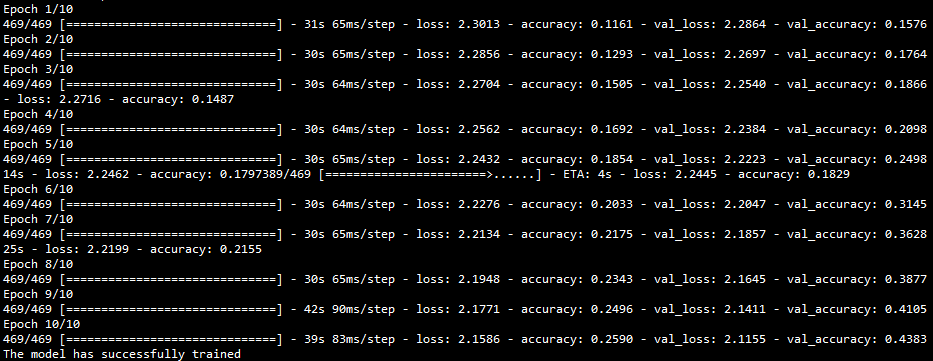
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Assignment 4

***ReLU vs. Sigmoid***

The rectified linear unit (ReLU) activation function produced a model that was 44% accurate after when 10 epochs were executed (Fig. 1). In order to increase the accuracy to around 90%, 50 epochs were required and this took about 40 minutes to execute. The Sigmoid activation function did not generate very useful results and produced a model with an accuracy of roughly 10% after 10 epochs (Fig. 2). When the number of epochs were increased the accuracy did not improve at all. This behavior shown by the sigmoid activation function seems to be due to the vanishing gradient problem that can be encountered when the model contains too many hidden layers. In an attempt to alleviate this issue, I reduced the number of hidden layers but the accuracy did not seem to improve at all unfortunately.

While the ReLU and Sigmoid activation models produced models with very different accuracy values, they both seemed to compile at a similar rate (~30s/epoch) which is unexpected since the Sigmoid activation model should have converged faster.



*Fig. 1*: Result of training model using a ReLU activation function. Accuracy increases after each successive epoch.



*Fig. 2*: Result of training model using a sigmoid activation function. Accuracy does not increase after each successive epoch.

***PC vs. Raspberry Pi***

The graphical user interface portion of the program ran relatively smoothly on my PC and using the ReLU model derived after 50 epochs, the accuracy of the predictions was very high (Fig. 3).

Running the same graphical user interface program on the Raspberry Pi 4 was much more difficult due to setup issues. The final solution to these issues was to install Tensorflow v.2.3.1 using “pip3 install https://github.com/lhelontra/tensorflow-on-arm/releases/download/v2.3.0/tensorflow-2.3.0-cp37-none-linux\_armv7l.whl” and this allowed me to use the default version of Keras that is installed (v.2.3.1) rather than a downgraded version. When the program was run on the Raspberry Pi 4 using the same model that was generated on the PC, the results were similar in terms of accuracy but took slightly longer to generate predictions. The delay was not noticeable at the beginning but began to feel somewhat noticeable the longer the Raspberry Pi 4 was on. This buildup of heat was caused by a small HD screen “hat” being mounted on the Raspberry Pi 4 and a lack of convection to prevent a buildup of heat.



*Fig. 3*: Graphical user interface showing a prediction based on a hand-drawn number. This model utilized a ReLU activation function run for 50 epochs to achieve a high accuracy.